

Total No. of Questions : 8]

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Roll No

EX-602**B.E. VI Semester**

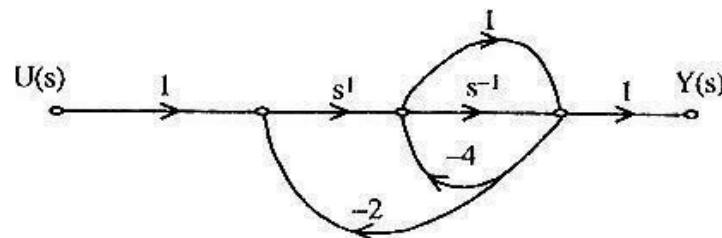
Examination, June 2017

Control System**Time : Three Hours****Maximum Marks : 70**

- Note:** i) Attempt any five questions out of eight questions.
 ii) All questions carry equal marks.
 iii) Assume suitable data, if required.

- Write a short note on Mason's Gain Formula which is used for solving signal flow graph.
 - What are the basic differences between open and closed loop control system and which one is preferred mostly and why?
- Write down the advantages and disadvantages of transfer function approach.
 - The signal flow graph for a system is given below. Find

the transfer function $\frac{Y(s)}{U(s)}$. **www.rgpvonline.com**



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- Explain the concept of Relative Stability and Absolute Stability.
 - Write a short note on standard test signals for analyzing the time response of any control system.

- For a unity feedback control system the forward path gain

$$G(s) = \frac{k}{s(s+2)(s^2+2s+2)}, \text{ then find the value of } k \text{ for}$$

which the Root-locus crosses the imaginary axis and also find the value of angle of departure for complex roots.

- For a unity feedback control system having its forward path transfer functions as, $G(s) = \frac{20}{(s+1)(s+5)}$.

Determine characteristics equation of the system ω_n , ω_d , t_p , M_p , damping factor and time at which First overshoot occurs.

- Write a short note on the advantages of Bode plot.
 - The limitation of root locus analysis is over come by Bode plot, this sentence is true or false, explain in details.
- Explain the term Gain Margin.
 - Draw the Nyquist plot for

$$G(s) \cdot H(s) = \frac{1}{s^2(1+sT_1)(1+sT_2)} \text{ and make a comment}$$

on stability. **www.rgpvonline.com**

- Write down the advantages of phase lead-lag compensation network.
 - Explain the PID Controller in Details.
- Write short note on State space and State variable.
 - Explain the relationship in between the state equation and transfer function.
