

UNIT – 2

FOURIER TRANSFORM

Syllabus: Integral Transforms: Fourier Transform-Complex Fourier Transform, Fourier Sine and Cosine Transforms, Applications of Fourier Transform in Solving the Ordinary Differential Equation.

Any general periodic signal has the automatic property $f(t) = f\left(\frac{2\pi t}{T}\right)$ where T is the period of the signal.

The 2π is “snuck” in because we know that trigonometric functions are good examples of repetition. The complexity of $f(t)$ is irrelevant as long as it repeats itself faithfully. Please keep in mind that ‘ t ’ for radioastronomy is usually time, but in fact it is an arbitrary variable and so what follows below is applicable provided the variable has functional repetition in some way with a repeat T . Thus spatial repetition is another important variable to which we may apply the theory.

Fourier discovered that such a complex signal could be decomposed into an infinite series made up of cosine and sine terms and a whole bunch of coefficients which can (surprisingly) be readily determined.

$$f(t) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} a_n \cos\left(\frac{2\pi nt}{T}\right) + \sum_{n=1}^{\infty} b_n \sin\left(\frac{2\pi nt}{T}\right)$$

If you like, we have decomposed the original function $f(t)$ into a series of basis states. For those of you who like to be creative this immediately begs the question of: is this the only decomposition possible? The answer is no.

The coefficients are “readily” determined by integration.

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos\left(\frac{2\pi nt}{T}\right) dt$$

$$b_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \sin\left(\frac{2\pi nt}{T}\right) dt$$

Introducing complex notation we can simplify all of the above to what you often see in textbooks.

$$f(t) = \sum_{n=-\infty}^{\infty} c_n \exp\left(-i \frac{2\pi nt}{T}\right)$$

$$c_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) \exp\left(i \frac{2\pi nt}{T}\right) dt$$

Here $c_0 = \frac{1}{2}a_0$, $c_n = \frac{1}{2}(a_n + ib_n)$, and $c_{-n} = \frac{1}{2}(a_n - ib_n)$.

The graphical example below indicates how addition of cosine time function terms are Fourier transformed into coefficients. In this case only $c_n = a_n / 2$. Take care the centre line with the big arrow is to mark the axis only – it is **not** part of the coefficient display. Notice also that **two** coefficient lines appear for every frequency. The latter is related to the Nyquist sampling theorem (see below) and is also why the coefficient magnitudes are halved. Notice also the **spacing** of the coefficients to be an integral multiple of $f_0 = 1/T$ with the sign consistent with the input waveform.

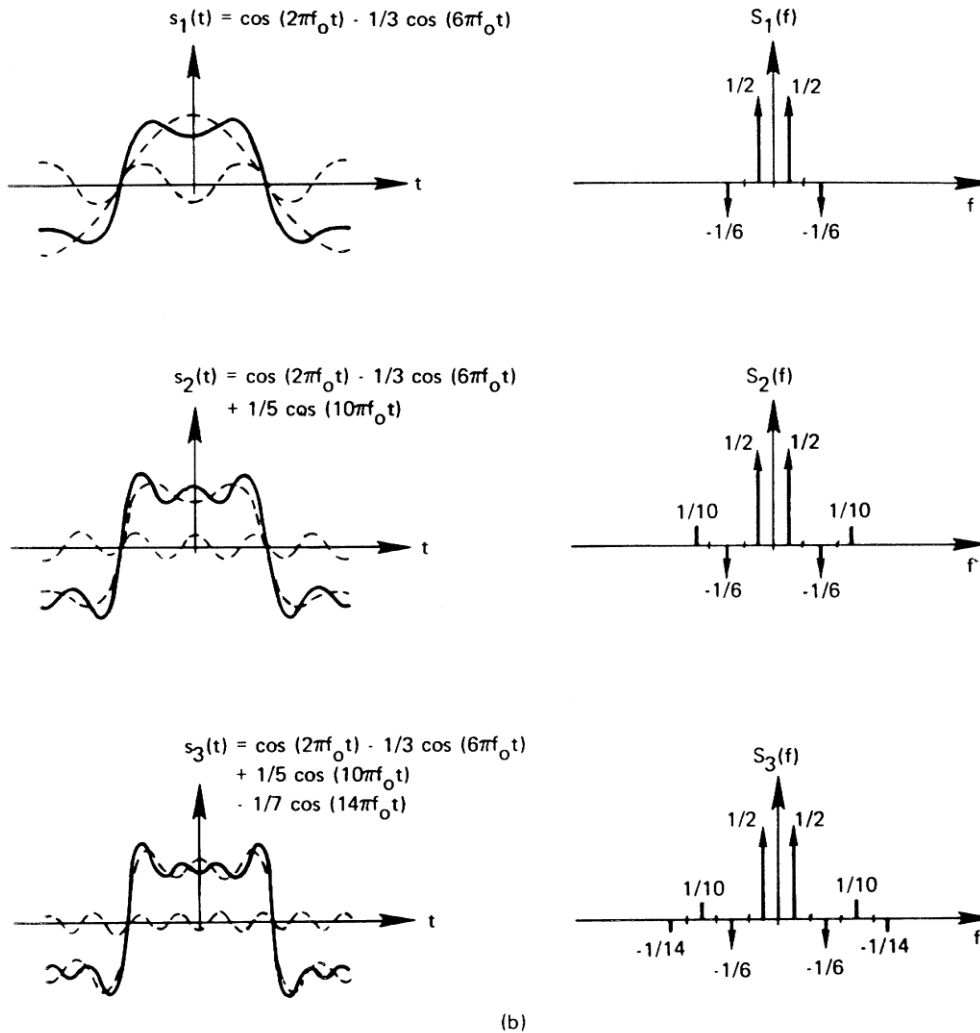


Fig. 2.1(after 'The Fast Fourier Transform', E.O. Brigham, Prentice Hall, 1974)

Exercise:

Q1. Find the Fourier transform of $f(x) = \begin{cases} x, & |x| \leq a \\ 0, & |x| > a \end{cases}$

Soln. $F\{f(x)\} = \int_{-a}^a x e^{isx} dx$ =

$$\frac{2a}{is} \left(\frac{e^{isx} + e^{-isx}}{2} \right) - \frac{1}{(is)^2} (e^{ias} - e^{-ias})$$

$$F\{f(x)\} = \frac{2i}{s^2} (sinas - a cosas)$$

Q2. Find the Fourier sine transform of $f(x) = \begin{cases} sinx, & 0 < x < a \\ 0, & x > a \end{cases}$

$$\text{Soln. } f_s(s) = \sqrt{\frac{2}{\pi}} \int_0^\infty f(x) sin sx dx$$

$$\begin{aligned}
&= \sqrt{\frac{2}{\pi}} \int_0^a \sin x \sin s x \, dx + 0 \\
&= \frac{1}{2} \sqrt{\frac{2}{\pi}} \int_0^a (\cos(s-1)x - \cos(s+1)x) \, dx \\
&= - \left[\frac{\sin(s-1)a}{s-1} - \frac{\sin(s+1)a}{s+1} \right]
\end{aligned}$$

Thinking in terms of the Fourier Transform

- Digital filtering on a static input time sample can be done taking a FFT of the vector and then applying the desired filter shape to the resultant coefficients. Now apply an inverse FFT and the result is a filtered time set. Clean up your old records this way by converting the sound to digital sample files and process them on a PC.
- Continuous digital filtering on a continuous time sample can be thought of as deliberately convolving the incoming signal with a function which is the inverse FT of the filter shape. This is how many digital filters called FIR filters work. They do the job on the fly.

There are a number of techniques to do FFT's quickly and so get power spectra. Correlators use the following simple idea:

1. The autocorrelation of a signal $f(t)$ with a time shifted version of itself $f(t + \tau)$ is given by
$$A(\tau) = \int f(t)f(t + \tau)dt .$$
2. If we take the FT of this in τ space we get, after a fiddle with variable substitution,
$$\int A(\tau)\exp(i2\pi s\tau)d\tau = F(s)F^*(s),$$
provided we assume $f(t)$ is a real function (which of course it will be in our case). But this is exactly the desired power spectrum since $P(s) = F(s)F^*(s)$.
3. Producing a fast autocorrelator using a shift register and a bit of electronics allows $A(\tau)$ to be produced efficiently by continually multiplying a sampled signal with previous samples of itself. The final vector can then be converted into a power spectrum with a single FFT.

The Fourier “Family(Another way to study Fourier)

Fourier Series

If we have a reasonably well behaved, continuous, periodic function $x(t)$, then we can approximate $x(t)$ as the weighted sum of simple sinusoids

$$\text{e.g. } x(t) \approx a_0/2 + \sum_n (a_n \cos(2\pi ft) + b_n \sin(2\pi ft))$$

if we choose the “weights” a_n and b_n properly. A simple “least squares” procedure yields the well known formulae for calculating a_n and b_n , i.e.

$$a_n = (2/T) \int_{-T/2}^{T/2} x(t) \cos(2\pi ft) dt$$

$$b_n = (2/T) \int_{-T/2}^{T/2} x(t) \sin(2\pi ft) dt$$

where $f = n/T$

We can use Euler’s relation to rewrite the sinusoidal version of Fourier series in terms of exponentials, e.g.

$$x(t) = \sum_n \alpha_n e^{i2\pi ft}$$

$$\text{where } \alpha_n = (1/T) \int_{-T/2}^{T/2} x(t) e^{-i2\pi ft} dt$$

In the limit of the period T approach infinity, we get the a fit to a non-periodic function $x(t)$ that is the

Fourier Transform

$$\mathbf{X}(f) = \int_{-\infty}^{\infty} x(t) e^{-i2\pi ft} dt$$

which converts a function of time into a function of frequency
(or a function of space into a function of wavenumber)

$x(t)$ is then represented by $\mathbf{X}(f)$

The new function has the same information as $x(t)$ but from a different perspective. If this is done properly, then one can always recover the original function $x(t)$ by an **inverse transform**, i.e.

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{+i2\pi ft} dt$$

The discrete (digital) form of the transform (**DFT**) for a time series of length N is:

$$X(j\Delta f) = X_j = \sum_{k=0}^{N-1} x_k e^{-i2\pi kj/N}$$

and

$$x(k\Delta t) = x_k = 1/N \sum_{j=0}^{N-1} X_j e^{i2\pi kj/N}$$

where $\Delta f = 1/N \Delta t$

Note the relationship with simply sinuisoids, i.e.

$$e^{-i2\pi kj/N} = \cos(2\pi kj/N) - i \sin(2\pi kj/N)$$

Also note that these equations allow one to compute either X or x for values of j and i respectively that are outside the range of 0 and $N-1$. These values correspond to the periodic replicas of X and x that are implicit in the discrete formulation.

Now, let's make a simple substitution, letting

$$z = e^{-i2\pi j/N}$$

then the equation for the DFT becomes

$$X(j\Delta t) = X_j = \sum_{k=0}^{N-1} x_k e^{-i2\pi kj/N} = \sum_{k=0}^{N-1} x_k z^k = X(z).$$

This latter relation is called the

Z transform.

Note that computing the Z transform for a time series is rather trivial:

e.g. if $x_k = 1, 4, 0, -8, 3$

then

$$X(z) = 1z^0 + 4z^1 + 0z^2 - 8z^3 + 3z^4$$

or
$$X(z) = 1z + 4z^1 - 8z^3 + 3z^4$$

This real utility of the z transform becomes apparent when implementing convolution via the convolution theorem, i.e.

given x_t as the input to filter f_t , then the output is:

$$s_t = x_t * f_t$$

Using the convolution theorem, this is equivalent to:

$S(z) = X(z) \cdot F(z)$, where these are the z transforms of the their respective time series.

ex. if $x_t = 1, 3$ and $f_t = 4, 2$ then

$$S(z) = (1+3z) \cdot (4+2z) = 4 + 14z + 6z^2 \text{ (i.e. polynomial multiplication)}$$

or $s_t = 4, 14, 6$

Deconvolution with the z transform

Z transforms are also very handy for computing inverse filters (deconvolution)

Again, if $s_t = x_t * f_t$ and $S(z) = X(z) \cdot F(z)$.

If we want to compute x_t from s_t and f_t , then

$$X(z) = S(z)/F(z) \quad \text{or} \quad X(z) = S(z) \cdot F^{-1}(z)$$

Where $F^{-1}(z) = 1/F(z)$ is the inverse filter for $F(z)$.

We can computer $F^{-1}(z)$ directly by polynomial division:

Example: if $f_t = 2, 1$ and $F(z) = 2+z$,

then $F^{-1}(z) =$

$$\begin{array}{r} \underline{.5 \ - .25z \ + .125z^2 \ - .0625z^3 \ + \dots \ \text{etc.}} \\ 2+z \ | \ 1 \\ \underline{1 + .5z} \\ \quad \quad \quad -.5z \\ \quad \quad \quad \underline{-.5z - .25z^2} \\ \quad \quad \quad \quad \quad \quad .25z^2 \end{array}$$

This form of $F^{-1}(z)$ is called an **Infinite Impulse Response Filter** or **IIR**.

Note that since the higher order terms are decreasing in amplitude, this infinite series is convergent. Thus it is **stable**. This is the case
