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- a) Explain the different methods of scheduling in multiprocessor and distributed systems.
 - b) Explain the priority inheritance protocol.
- a) Explain the task scheduling and task management process.
 - b) Explain the various performance metrics of real time operating system?
- a) What do you mean by porting of COS II? Discuss general requirements of processor to port COS II along with hardware/software architecture.
 - b) Describe the role of UNIX as a real time operating system. Explain inter process communication in UNIX environment.
- 8. Explain the following:
 - i) Host target approach
 - ii) Fully pre-emptible kernel

Total No. of Questions :8]

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MEVD - 202 M.E./M.Tech., II Semester

Examination, June 2014

Real Time Operating System

Time: Three Hours

Maximum Marks: 70

Note: i) Attempt five questions.

- ii) Each question carry equal marks.
- a) What are the components of a real time system? Draw schematic block diagram of real time system.
 - b) Discuss the problems faced in the design and implementation of an operating system.
- a) Explain the inter process communication in message passing systems with suitable example.
 - b) Explain the file system organization.
- What is binary semaphore? With an example explain how to use binary semaphores for signaling or notifying occurrences of an event from a task or thread and for signaling or notifying another task waiting for that event.
- 4. Prove the theorem with figures: When preemption is allowed and jobs do not contend for resources, the EDF algorithm can produce a feasible schedule a set of jobs J with arbitrary release times and deadlines on a processor if and only if J has feasible schedules.